

# CIF21 DIBBs: Ubiquitous Access to Transient Data and Preliminary Results via the SeedMe Platform

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Open source ✓

Web based ✓

Cross-platform ✓

## What is SeedMe?

**SeedMe = Stream Encode Explore and Disseminate My Experiments**

SeedMe is a platform that enables easy sharing of transient and preliminary data for a broad research computing community by offering cyberinfrastructure as a service and a modular software stack that may be customized. SeedMe is based on Drupal content management system with a set of building blocks with additional PHP modules and web services clients.

## Significant results

✓ Federated authentication	Virtual File System
✓ Small Data Visualization	Small Data API ✓
✓ Pilot project with 580+ registered users 120,000+ content items Integration with four scientific tools	Early demonstration prototype ✓

✓ Available

## Why build a platform?

Research computing is highly collaborative, distributed and often uses disparate compute resources. Currently available tools do not meet sharing and collaborative needs that must collocate data, description and discussion (3D) and additionally handle transfer, storage and access control. Furthermore, these tools must be cross platform and readily pluggable for automation with existing scientific workflows.

## For whom?

- Computing researchers**
  - Collaboration hub
  - Personal dashboard
- Developers**
  - Integrate with scientific applications
- Project repositories**
- Gateways**
  - Service for data sharing, data publishing, data escrow
- CI providers:** Offer the platform to your user base

## Use how?

- As a cloud service**
    - [dibbs.seedme.org](http://dibbs.seedme.org)
    - [www.seedme.org](http://www.seedme.org)
  - DIY - Run own instance**
    - On your own hardware
    - Condo hardware
  - Provider run instances**
    - At your institution
    - At national centers
    - At public cloud
- No lock in**

## Planned building blocks

Federated authentication + Authorization	Virtual File System	Access Control
Sharing	Search / Index	Microformats
Field Formatters	REST API	Clients (Java, Python) + Command Line
Light Visualization	Rich Text	Discussion

## Virtual file system: Sample UI

Home / Projects / Benchmarking OpenGL performance for mesh visualization / View

OpenGL mesh memory use

Benchmark: OpenGLTest  
Run dates: July-August 2015

Table of contents: Description, Observations, Conclusions, Files

**Description**  
The OpenGLTest benchmark measures mesh memory use for each of four mesh types and several rendering styles for each type:

- Point cloud varying point size - a point is drawn at each cell, while point color and size vary with the cell value.
- Point cloud varying point opacity - a point is drawn at each cell, while point color and opacity vary with the cell value.
- Polygon layers varying color - a grid of polygons are drawn for each vertical layer in the mesh, varying color and opacity with cell values.
- Polygon layers varying texture - a grid of polygons are drawn for each vertical layer in the mesh, varying opacity and texture coordinates for a texture image with color varying by cell values.
- Polygon faces varying color - each face of each cell in the mesh is drawn, varying color and opacity with cell values.
- Polygon faces varying texture - each face of each cell in the mesh is drawn, varying opacity and texture coordinates for a texture image with color varying by cell values.

**Observations**  
As expected, different rendering styles have different memory requirements. A style that draws a polygon for every cell face, for instance, requires much more memory than one that only draws a point for every cell. Texture mapping for regular meshes with planar layers replaces a lot of color values for cell vertices with a similar set of texture coordinates, reducing memory use. However, texture mapping for the other mesh types has no benefits since it just replaces color values with equivalent texture coordinate values at every coordinate, making mesh memory use the same.

**Conclusions**  
All scene data must be built and stored on the host, then transferred in pieces to the GPU for rendering. The maximum scene size is limited by the amount of host physical memory, not by the GPU. Different types of meshes and different rendering styles for those meshes has a substantial impact on the amount of memory required to create and fill vertex buffers to draw the meshes.

Name	Changed	Size
Data	Fr, 09/09/2016 - 14:09	---
Images	Fr, 09/09/2016 - 14:05	---

## Light visualizations

**Example - Image classification work breakdown schedule**

File format: JSON  
Schema: json-tree  
Table rows: 72  
Table columns: 2

**Example - Benchmark times for image preprocessing using C++**

File format: JSON  
Schema: table  
Table rows: 7  
Table columns: 6

**Example - OpenGL mesh memory use as mesh sizes scale up**

File format: CSV  
Schema: table  
Table rows: 20  
Table columns: 7

**Example - Benchmark times for image preprocessing using Matlab**

File format: JSON  
Schema: table  
Table rows: 10  
Table columns: 9

## Project information

Website: <https://dibbs.seedme.org>

- Cross-platform tools, APIs, and Drupal modules
- Post & query data from HPC jobs, workflows, apps, browsers, and command line
- Cloud file system for secure data sharing and collaboration
- Integrated lightweight visualization tools for quick analysis
- Secure access, sharing, and access controls

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